Resum de Tesi Doctoral



DNI/NIE/Passaport	Y0317475C
Nom i cognoms	FABIO ANDRADE RENGIFO
Títol de la tesi	STUDY OF STABILITY AND NON-LINEAR CONTROL APPLIED TO MICROGRID
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Resum de la tesi de 4000 caràcters màxim (si supera els 4000 es tallarà automàticament) The "inertialess" and intermittent production of renewable generators has increased significantly in recent years. Based on electronic converter interfaces, intermittent generators such as photovoltaic devices or windmills are connected, stored and managed by a smart control system for supplying energy to local consumers. Such a system is known as a Microgrid. The modern power generators connected in Microgrid are highly efficient, reliable, modular, environmentally friendly, noiseless, and controlled with high precision. Because of this, they will be a significant competitor in future power markets. In the state of the art for the study of the Microgrid stability several models for power generators are suggested. They show a clear predominance of inverters in parallel connection controlled by voltage and current loops, using the droop curves of the relationships between active power vs. requency and reactive power vs. voltage. These models have been generally linearized at an operating point and they could operate under small perturbations. Authors have studied and identified the roots of the system in the complex plane. Furthermore, how the roots are moving depending on small variations of system parameters, parameters such as slopes of the droop curves, line impedances, etc. have ben also studied. However, these models are only valid while the system does not undergo large variations around this operating point. Therefore, these models do not reflect a reality in Microgrids when they suffer major changes, for example the connection or disconnection of the public grid in unexpected ways, or intermittent generation sources. As they are based on renewable energy, they can pass to deliver maximum power to not deliver power at very short times due to an unexpected change in the environment. This thesis applies the current theory of nonlinear systems analysis, such as Lyapunov methods, procedures Popov and phase planes,	
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