

# Field Programmable Arrays for Neuromorphic Computation

#### **Alister Hamilton**

14<sup>th</sup> & 15<sup>th</sup> June 2010 UPC, Barcelona



#### Talks Schedule

#### 14<sup>th</sup> June 2010: Neuromorphic Systems in Analogue VLSI: developments at the University of Edinburgh

#### 15<sup>th</sup> June 2010: Programmable Analogue VLSI Architectures: two novel approaches



# Neuromorphic Systems in Analogue VLSI: development at the University of Edinburgh

#### **Alister Hamilton**

14<sup>th</sup> June 2010 UPC, Barcelona



# Agenda

- Neural Network implementations
  - Pulse stream and pulse width schemes
  - Epsilon chip and applications
- Neuromorphic Systems
  - Integrate and Fire neurons in auditory system
  - Adaptive Neuromorphic Olfaction Chip
  - Cricket hair sensor
  - MEMS/CMOS microphone



#### Neural network implementations

 $T_{0,0}$ 

- Synapse multiplies incoming pre-synaptic neural state (V<sub>j</sub>) by a synaptic weight (T<sub>ii</sub>).
- *Synapse* outputs are *summed* in each column.
- Non-linear neuron generates post-synaptic neural state (S<sub>i</sub>).

 $\begin{array}{c} \mathbf{u} \\ \mathbf{a} \\ V_{1} \rightarrow T_{0,1} \\ V_{2} \rightarrow T_{0,2} \\ V_{3} \rightarrow T_{0,3} \\ \mathbf{u} \\ \mathbf{m} \\ \mathbf{n} \\ \mathbf{n}$ 

Synapse array



### Information encoded in time (#1)







#### Implementation strategy

- Encode neural states as PWM or PFM signals
  leads to a new range of circuit implementations
- Encode synaptic weights as analogue voltages
  - Stored on capacitors locally at each synapse
  - Refreshed from off-chip RAM
  - Refresh mechanism updates each synaptic weights





 $V_i$ : a digital pulse or series

### Implementation in analogue VLSI

Novel implementations inspired by biology

- Example column of synapses

of pulses represents the 2Vref pre-synaptic neural state. Vsz M4 M1Vouti M3 Tij 🗗 Vref 🕞  $T_{ii}$ : analogue voltage Synapse column M5 Vbias represents output synaptic weight GND



#### Neuron implementation

• Neuron output represented by a digital *width modulated pulse*, or a *stream of digital pulses*.





#### Pulse stream neuron





### Pulse stream neuron gain change

Modify the slope of the transfer characteristic
realised using phase lock loop mechanisms





### Variable gain neuron circuit

• Two diff stages provide sigmoid & gain control





#### Pulse width neuron

• Simple comparator fed with a (linear) ramp.





#### Pulse width neuron ramp control

Simple comparator fed with a non-linear ramp.
– non-linear ramp generated off-chip (RAM and DAC)





# **EPSILON** Outline

- Edinburgh Pulse Stream Implementation of a Learning Oriented Network
  - 120 inputs, 30 outputs
  - 3600 synapses
  - 18Mcps 360Mcps
  - 9.5mm x 10.1mm in
     1.5μm CMOS





# **EPSILON:** chip photo





# System integration

#### • EPSILON chips and support circuitry on a PCB





# Oxford/Alvey vowel database

- Vowel sounds from 18 female and 15 male speakers
  - Analogue outputs from a bank of 54 band-pass filters
  - Feedforward network of 54 input neurons, 27 hidden layer neurons and 11 output neurons
  - Network trained with 2 female speakers using a virtual target training algorithm (similar to back propagation)
  - Network then presented with remaining 16 female speakers to test generalisation performance.



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### Mean square error results

Mean square error reduced as training progresses
Initial weight set developed on workstation
Chip-in-loop training follows. (a) system reset.



![](_page_19_Picture_0.jpeg)

### Generalisation performance

- EPSILON chip
  - 65%
- Workstation trained on the same data and seeded with 20 random weight sets achieved
  - Minimum 48%
  - Maximum 68%
  - Mean 58%
- EPSILON comparable with workstation performance on this simple test

![](_page_20_Picture_0.jpeg)

#### Variations on a theme

- Simpler more "*portable*" synapse
  - easier to port between projects and processes
  - larger circuit, but *much* less complexity

![](_page_20_Figure_5.jpeg)

![](_page_21_Picture_0.jpeg)

#### The dynamic current mirror

- Allows currents to be matched across large synaptic arrays.
- Synaptic weights represented by currents derived from simple on-chip current digital to analogue converter.

![](_page_21_Figure_4.jpeg)

![](_page_22_Picture_0.jpeg)

#### Integrate & Fire Neurons in Auditory Systems

![](_page_23_Picture_0.jpeg)

### Information encoded in time (#2)

- EPSILON neuron model makes use of time but neuron model is simplistic
- Integrate and Fire neuron model is a step nearer the biological neuron
  - Leaky integration of input current, neuron spikes once threshold reached

![](_page_23_Figure_5.jpeg)

![](_page_24_Picture_0.jpeg)

# Sound Segmentation

- Integrate and Fire neurons useful for processing signals that vary with time
- Analogue VLSI of an integrate and fire system to detect onsets and offsets in speech

![](_page_24_Figure_4.jpeg)

![](_page_25_Picture_0.jpeg)

### Slowing down the I&F neuron

#### • I&F neuron input stage

![](_page_25_Figure_3.jpeg)

![](_page_26_Picture_0.jpeg)

### Synapse implementation

![](_page_26_Figure_2.jpeg)

![](_page_27_Figure_0.jpeg)

![](_page_28_Picture_0.jpeg)

# Clap sounds: zooming in

50 mS of results from the I&F network in aVLSI
A: i/p = 0.25 FS, dissipation = 10; B: i/p = 0.5 FS, dissipation = 20; C: i/p = 1.0 FS, dissipation = 40

![](_page_28_Figure_3.jpeg)

![](_page_29_Picture_0.jpeg)

#### Adaptive Neuromorphic Olfaction Chip

![](_page_30_Picture_0.jpeg)

### Information encoded in time (#3)

- Integrate and Fire neuron model is a step nearer the biological neuron
  - Leaky integration of input current, neuron spikes once threshold reached
- But synapse model used so far takes no account of the time of occurrence of pre- or post-synaptic neural firing
  - several models exist of time dependent synapses

![](_page_31_Picture_0.jpeg)

#### Time dependent synapse function

• The *exponential summing* synapse

$$i_{BA}(t) = \Theta(t)\omega_{BA} e^{\frac{-t}{\tau_d}}$$
$$I_{BA}(t) = \sum_n i_{BA}(t - t_n)$$

- Synapse output
  - Pre-synaptic spike event period = 23mS,  $V_{\text{wt}}$  =

![](_page_31_Figure_6.jpeg)

![](_page_32_Picture_0.jpeg)

### Spike time dependent weight adaption

- Egger et al. 1999 Song et al. 2000
  - Synaptic weight change based on *pre* and *post* synaptic *spike time correlation*

![](_page_32_Figure_4.jpeg)

![](_page_33_Picture_0.jpeg)

# Spike time dependent weight adaption

- Dan et al. 1992 Gerstner et al. 1996
  - Synaptic weight change based on *pre* and *post* synaptic *spike time correlation*

![](_page_33_Figure_4.jpeg)

![](_page_34_Picture_0.jpeg)

#### RY CHANNEL ANALOO SENSOR ARRAY VLSI CHIP SIGNAL CONDITIONING CIRCUITRY ON-CHI STDP WEIGHT ADAPTIO NEUROMORPHIC CIRCUITS P(t)

- Electronic nose project
- Integration of
  - odour delivery mechanism
  - chemical sensor array + adaptive analogue interface
  - neuromorphic analogue VLSI
- Neuromorphic analogue VLSI
  - integrate and fire neurons
  - exponential summing synapses with weight adaption

![](_page_35_Picture_0.jpeg)

# Odour delivery & adaptive interface

- Odour delivered via a *micro-channel* on top of chip.
- Micro-channel delivers odour to sensor array.
- Programmable current sources bias sensors.
- Set-up phase cancels sensor DC offsets.

![](_page_35_Picture_6.jpeg)

![](_page_35_Picture_7.jpeg)

![](_page_36_Picture_0.jpeg)

### Odour sensors on chip

- Carbon black polymer materials deposited between two sensor electrodes.
- Exposure to gas causes sensor material to *swell* increasing resistance.
- Sensor embedded with adaptive analogue interface.

Resistive sensor electrodes

![](_page_36_Picture_6.jpeg)

![](_page_36_Picture_7.jpeg)

![](_page_37_Picture_0.jpeg)

#### Odour sensor responses

![](_page_37_Figure_2.jpeg)

- Responses to ethanol and toluene vapour in air
- Sensor responses *distinct* to each analyte
- Neuromorphic circuits extract spatio-temporal information from odour sensor array Dr Alister Hamilton, School of Engineering, University of Edinburgh 38

![](_page_38_Picture_0.jpeg)

#### Neuromorphic architecture

![](_page_38_Figure_2.jpeg)

![](_page_39_Picture_0.jpeg)

#### On chip weight adaption

![](_page_39_Figure_2.jpeg)

![](_page_39_Figure_3.jpeg)

- Weight adaption due to pre-synaptic spikes preceeding post-synaptic spikes (*left* traces)
- Weight adaption due to pre-synaptic spikes *following* post-synaptic spikes (*right* traces)

![](_page_40_Picture_0.jpeg)

### Neuromorphic network response

• Principal neuron fires as a result of synchronous excitation by the receptor neurons.

![](_page_40_Figure_3.jpeg)

![](_page_41_Picture_0.jpeg)

# Neuromorphic Olfaction Chips

- Chip #1: Sensor array
  - 70 resistive sensors and offset cancellation interface
- Chip #2: Neuromorphic circuits
  - 3 receptor neurons, 27 synapses and 1 principal neuron; learning off-chip
- Chip #3: Adaptive neuromophic olfaction chip
  - On-chip chemosensor array, on-chip sensor interface and neuromorphic olfactory circuits with on-chip STDP learning.

![](_page_42_Picture_0.jpeg)

# Adaptive Neuromorphic Olfaction Chip: Performance Summary

Parameter	Values
Supply Voltage	5V
Area	6.5mm <sup>2</sup>
Sensor Resistance	$10 \text{ k}\Omega - 200 \text{ K}\Omega$
Sensor driving current	1 μΑ, 10 μΑ, 100 μΑ
Sensor bandwidth	< 1 Hz
Sensor DC baseline variation	± 1 V
Input referred DC offset	$< \pm 5 \text{ mV}$
Prog. Amplifier gains	10, 10, 1000
Synaptic time constant	10 ms – 300 ms
Weight range	$\pm 1 \text{ V}$
Neuron time constant	10 ms – 300 ms
Neuron spike width	$10 \ \mu s - 1 \ ms$
Neuron refractory time period	10 ms – 300 ms

![](_page_43_Picture_0.jpeg)

#### Cricket Hair Wind Sensor

![](_page_43_Picture_2.jpeg)

![](_page_44_Picture_0.jpeg)

# **Robot Crickets**

- Robot modeling of a cricket's escape response
  - Robot with artificial cercal wind sensors and neural model for escape response
  - Can we use MEMS to make wind sensors?

![](_page_44_Figure_5.jpeg)

![](_page_45_Picture_0.jpeg)

# MEMS wind sensor

![](_page_45_Figure_2.jpeg)

![](_page_46_Picture_0.jpeg)

![](_page_46_Figure_1.jpeg)

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![](_page_47_Picture_0.jpeg)

#### MEMS/CMOS microphone

![](_page_48_Picture_0.jpeg)

### Implement bandpass filters in MEMS

![](_page_48_Figure_2.jpeg)

![](_page_49_Picture_0.jpeg)

# Resonant Gate Transistor (RGT)

#### • Acts as a transducer for incoming acoustic signal

![](_page_49_Figure_3.jpeg)

![](_page_50_Picture_0.jpeg)

# Array of RGTs

Array of RGTs implement audio bandpass filters
 Adaptive gain can be implemented by controlling gate bias voltage

![](_page_50_Figure_3.jpeg)

![](_page_51_Picture_0.jpeg)

# Manufactured MEMS bridges

• View at anchor of the bridge

![](_page_51_Figure_3.jpeg)

• View at the middle of the bridge

![](_page_51_Figure_5.jpeg)

![](_page_52_Picture_0.jpeg)

# Conclusion

- Neural and neuromorphic circuits presented process analogue signals in time.
  - Initially simply a convenience but increasingly
  - static neuron and synapse models give way to time dependent models
- Research focused on early neuromorphic signal processing
  - Olfaction, wind sensing and audition

![](_page_53_Picture_0.jpeg)

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